# Chapter 791

# Group-Sequential T-Tests for One Mean (Simulation)

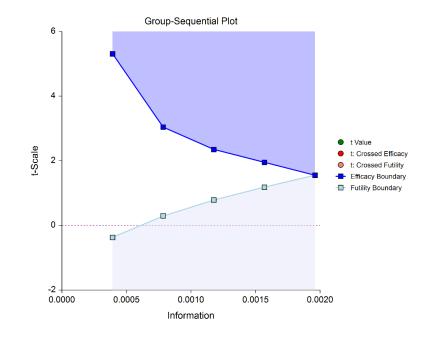
*In this procedure, boundaries are calculated analytically, while simulation is used for the calculation of power (and sample size). A variety of futility boundary options are available.* 

The corresponding analysis and sample size re-estimation procedure, found in NCSS Analysis and Graphics software, is <u>Group-Sequential T-Tests for One Mean</u>.

# Introduction

This procedure can be used to determine power, sample size and/or boundaries for group-sequential t-tests comparing a single mean to a hypothesized mean. For one- and two-sided tests, efficacy and/or futility boundaries can be generated. The spacing of the stages can be equal or custom specified. Individual stages may also be skipped. Boundaries can be computed based on popular alpha- and beta-spending functions (O'Brien-Fleming Analog, Pocock Analog, Hwang-Shih-DeCani Gamma family, linear) or custom spending functions, or boundaries may be input directly, if desired. Futility boundaries can be binding or non-binding. Corresponding P-Value boundaries are given for each boundary statistic (unless boundaries are input directly). Alpha and/or beta spent at each stage is reported. Plots of boundaries are also produced.

This procedure is used as the planning tool for determining sample size and initial boundaries. Stage data, as it is obtained, can be evaluated using the companion procedure *Group-Sequential T-Tests for One Mean*. The companion procedure also gives the option for sample-size re-estimation and updated boundaries for current-stage information. In that procedure, simulation can be used to evaluate boundary-crossing probabilities given the current stage results.



An example of a group-sequential boundary plot produced in this procedure is shown below.

# **Outline of a Group-Sequential Study**

There are three basic phases of a group-sequential (interim analysis) study:

- Design
- Group-Sequential Analysis
- Reporting

# **Design Phase – Determine the Number of Subjects**

To begin the group-sequential testing process, an initial calculation should be made to determine the sample size and target information if the final stage is reached (maximum information). The sample size calculation requires the specification of the following:

- Alpha
- Power
- Test Direction (two-sided or one-sided direction)
- Types of boundaries (efficacy, binding futility, non-binding futility)
- Maximum number of stages
- Proportion of maximum information at each stage
- Spending functions
- Within group standard deviation
- Assumed mean and null hypothesis mean

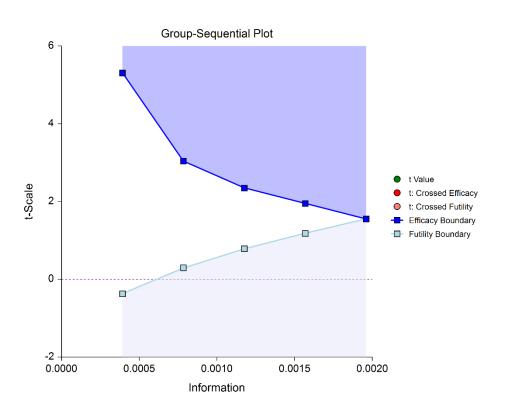
The design phase calculation is performed in this procedure. **PASS** software permits the user to easily try a range of means and standard deviations, as these values are typically not known in advance.

The resulting sample size of the sample size calculation also permits the calculation of the maximum information, which is the total information of the study if the final stage is reached (for calculation details, see the Information section later in this chapter).

Based on the maximum information, the target information and target sample size of each stage may be calculated. In particular, this permits the user to have a target sample size for the first stage.

Although it is likely to change over the course of the group-sequential analysis, a design group-sequential boundary plot can be a useful visual representation of the design:

#### Group-Sequential T-Tests for One Mean (Simulation)



# **Group-Sequential Analysis Phase**

A group sequential analysis consists of a series of stages where a decision to stop or continue is made at each stage. This analysis can be performed using the companion (analysis) procedure to this sample size procedure in **NCSS**.

### **First Interim Stage**

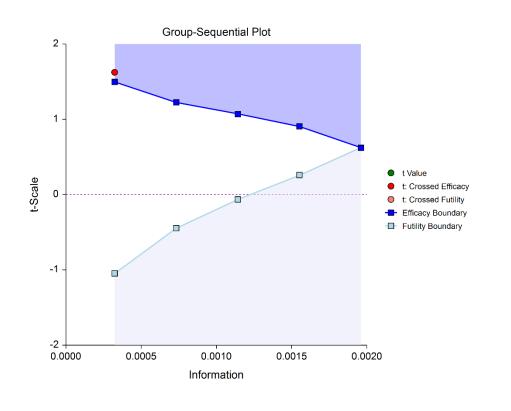
The design phase gives the target number of subjects for the first stage. The study begins, and response data is collected for subjects, moving toward the first-stage target number of subjects, until a decision to perform an analysis on the existing data is made. The analysis at this point is called the first stage.

Unless the number of subjects at the first stage matches the design target for the first stage, the calculated information at the first stage will not exactly match the design information for the first stage. Further, the sample standard deviation will rarely, if ever, match the standard deviation used in the calculation of the information at the design stage, and thus the calculated information at the first stage will differ from the design information. Generally, the calculated information will not differ too greatly from the design information, but regardless, spending function group-sequential analysis is well-suited to make appropriate adjustments for any differences.

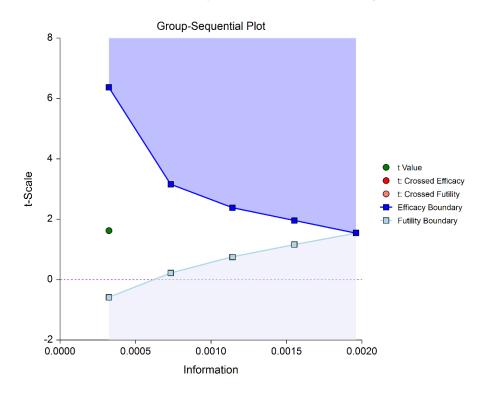
The first stage information is divided by the maximum information to obtain the stage one information proportion (or information fraction). This information proportion is used in conjunction with the spending function(s) to determine the alpha and/or beta spent at that stage. In turn, stage one boundaries, corresponding to the information proportion, are calculated.

A *t*-statistic is calculated from the raw mean difference and sample standard deviation. The stage one *t*-statistic is compared to each of the stage one boundaries. Typically, if one of the boundaries is crossed, the study is stopped (non-binding futility boundaries may be an exception).

#### Group-Sequential T-Tests for One Mean (Simulation)



If none of the boundaries are crossed the study continues to the next stage.



If none of the boundaries are crossed it may also be useful to examine the conditional power or stopping probabilities of future stages, using the **NCSS** procedure. Conditional power and stopping probabilities are based on the user-specified supposed true difference.

## Second and other interim stages (if reached)

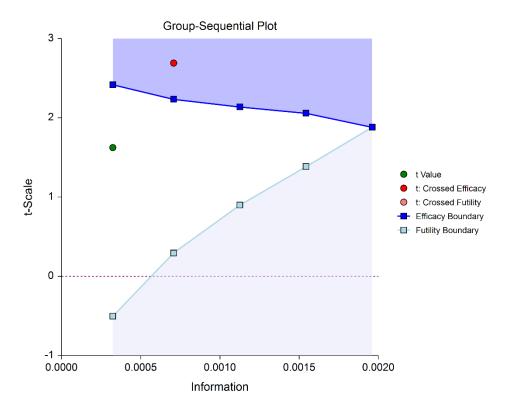
Since the first stage information proportion is not equal to the design information proportion, a designation must be made at this point as to the target information of the second stage. Two options are available in the **NCSS** procedure.

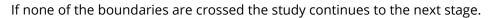
One option is to target the information proportion of the original design. For example, if the original design proportions of a four-stage design are 0.25, 0.50, 0.75, 1.0, and the stage one observed proportion is 0.22, the researcher might still opt to target 0.50 for the second stage, even though that now requires an additional information accumulation of 0.28 (proportion). The third and fourth stage targets would also remain 0.75 and 1.0.

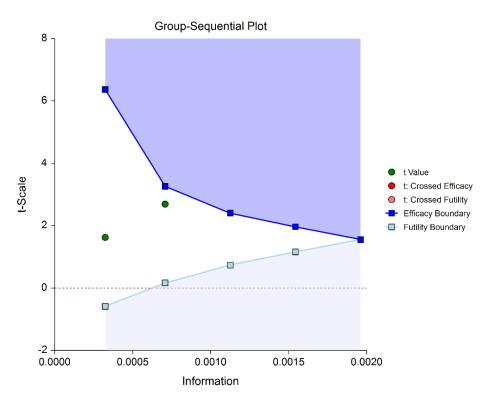
A second option is to adjust the target information proportionally to the remaining proportions. For this option, if the design proportions are 0.25, 0.50, 0.75, 1.0, and 0.22 is observed, the remaining 0.78 is distributed proportionally to the remaining stages. In this example, the remaining target proportions become 0.48, 0.74, 1.0.

For either option, once the target information is determined for the next stage, revised target sample sizes are given (in the **NCSS** procedure), and the study continues until the decision is made to perform the next interim analysis on the cumulative response data. In the same manner as the first stage, the current stage information proportion is used with the spending function to determine alpha and/or beta spent at the current stage. The current stage boundaries are then computed. The *t*-statistic is calculated and compared to the boundaries, and a decision is made to stop or continue.

If a boundary is crossed, the study is typically stopped.







Once again, if no boundary is crossed, conditional power and stopping probabilities may be considered based on a choice of a supposed true difference.

The study continues from stage to stage until the study is stopped for the crossing of a boundary, or until the final stage is reached.

### Final Stage (if reached)

The final stage (if reached) is similar to all the interim stages, with a couple of exceptions. For all interim analyses the decision is made whether to stop for the crossing of a boundary, or to continue to the next stage. At the final stage, only the decision of efficacy or futility can be made.

Another intricacy of the final stage that does not apply to the interim stages is the calculation of the maximum information. At the final stage, the current information must become the maximum information, since the spending functions require that the proportion of information at the final look must be 1.0. If the current information at the final stage is less than the design maximum information, the scenario is sometimes described as *under-running*. Similarly, if the current information at the final stage is greater than the design maximum information, the result may be termed *over-running*.

For both under-running and over-running, the mechanism for adjustment is the same, and is described in the Technical Details section, under Information and Total Information.

Aside from these two exceptions, the final stage analysis is made in the same way that interim analyses were made. The remaining alpha and beta to be spent are used to calculate the final stage boundaries. If the test is a one-sided test, then the final stage boundary is a single value. The final stage *t*-statistic is computed from the sample means and standard deviations of the complete data from each group. The *t*-statistic is compared to the boundary and a decision of efficacy or futility is made.

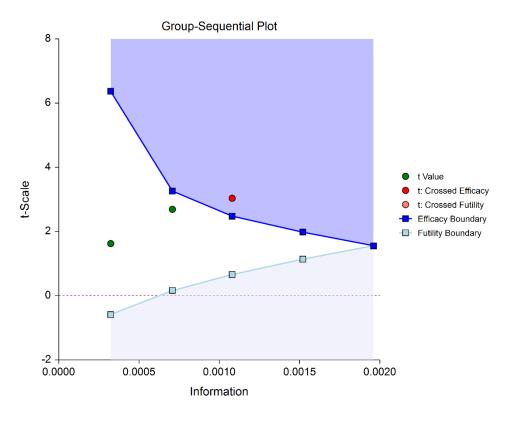
# **Reporting Phase**

Once a group-sequential boundary is crossed and the decision is made to stop, there remains the need to properly summarize and communicate the study results. Some or all of the following may be reported:

- Boundary plot showing the crossed boundary
- Adjusted confidence interval and estimate of the mean difference
- Sample size used

#### Boundary plot showing the crossed boundary

The boundary plot gives an appropriate visual summary of the process leading to the reported decision of the study.



#### Adjusted confidence interval and estimate of the mean difference

Due to the bias that is introduced in the group-sequential analysis process, the raw data confidence interval of the difference in means should not be used. An adjusted confidence interval should be used instead.

#### Sample size used

The sample size at the point the study was stopped should be reported in addition to the sample size that would have been used had the final stage been reached.

# **Technical Details**

Many articles and texts have been written about group sequential analysis. Details of many of the relevant topics are discussed below, but this is not intended to be a comprehensive review of group-sequential methods. One of the more influential works in the area of group-sequential analysis is Jennison and Turnbull (2000).

# **Null and Alternative Hypotheses**

For comparing a mean to a value, the basic null hypothesis is that of equality,

$$H_0: \mu = \mu_0$$

with three common alternative hypotheses,

$$H_a: \mu \neq \mu_0$$
 ,  
 $H_a: \mu < \mu_0$  , or  
 $H_a: \mu > \mu_0$  ,

one of which is chosen according to the nature of the experiment or study.

These hypotheses may be specified equivalently as

$$H_0: \mu - \mu_0 = 0$$
$$H_a: \mu - \mu_0 \neq 0$$
$$H_a: \mu - \mu_0 < 0$$
$$H_a: \mu - \mu_0 > 0$$

A slightly different set of null and alternative hypotheses are used if the goal of the test is to determine whether  $\mu_1$  or  $\mu_2$  is greater than or less than the other by a given amount.

The null hypothesis then takes on the form

$$H_0: \mu - \mu_0 = Hypothesized Difference$$

and the alternative hypotheses,

versus

 $H_{a}: \mu - \mu_{0} \neq$  Hypothesized Difference  $H_{a}: \mu - \mu_{0} <$  Hypothesized Difference  $H_{a}: \mu - \mu_{0} >$  Hypothesized Difference

For testing these hypotheses with a hypothesized difference, a superiority by a margin or non-inferiority test should be used instead.

# **Stages in Group-Sequential Testing**

The potential to obtain the benefit from a group-sequential design and analysis occurs when the response data are collected over a period of weeks, months, or years rather than all at once. A typical example is the case where patients are enrolled in a study as they become available, as in many types of clinical trials.

A group-sequential testing stage is a point in the accumulation of the data where an interim analysis occurs, either by design or by necessity. At each stage, a test statistic is computed with all the accumulated data, and it is determined whether a boundary (efficacy or futility) is crossed. When an efficacy (or futility) boundary is crossed, the study is usually concluded, and inference is made. If the final stage is reached, the group-sequential design forces a decision of efficacy or futility at this stage.

For the discussions below, a non-specific interim analysis stage is referenced as *k*, and the final stage is *K*.

# **Test Statistic**

The *t*-statistic for any stage *k* is obtained from all the accumulated data up to and including that stage, using

$$t_k = \frac{\bar{X}_k - \mu_0}{\sqrt{\frac{s_k^2}{n_k}}}$$

with degrees of freedom

$$df = n_k - 1$$

# **Group-Sequential Design Phase**

In most group-sequential studies there is a design or planning phase prior to beginning response collection. In this phase, researchers specify the anticipated number and spacing of stages, the types of boundaries that will be used, the desired alpha and power levels, the spending functions, the anticipated standard deviation, and an estimate of the true difference in mean from the null-hypothesized value.

Based on these input parameters, an initial set of boundaries is produced, an estimate of the total number of needed subjects is determined, and the anticipated total information at the final stage is calculated. This procedure can be used to make these planning phase sample size estimation calculations.

### **Information and Total Information**

In the group-sequential design phase, the final stage (*K*) or total (design) information is calculated from the specified standard deviation and the final sample size, as

$$I_K^* = \frac{1}{\frac{\sigma_K^2}{n_K}}$$

The information at any stage *k* may be calculated from the specified standard deviation and the sample size, as

$$I_k = \frac{1}{\frac{\sigma_k^2}{n_k}}$$

The planning  $\sigma$  is used for  $\sigma_k$ , since a realized value is not available before data is collected. When the analysis is carried out, the sample estimate  $s_k$  will be used in place of  $\sigma_k$ . The proportion of the total information (or information fraction) at any stage is

$$p_k = \frac{I_k}{I_K^*}$$

The information fractions are used in conjunction with the spending function(s) to define the alpha and/or beta to be spent at each stage.

To properly use the spending function at the final stage, it is required that  $p_K = 1$ . However, if the final stage is reached, we see that

$$I_{K} = \frac{1}{\frac{\sigma_{K}^{2}}{n_{Kachieved}}} \neq I_{K}^{*} = \frac{1}{\frac{\sigma_{K}^{2}}{n_{K}}}$$

so that

$$p_K = \frac{I_K}{I_K^*} \neq 1$$

When  $I_K > I_K^*$ , it is called over-running. When  $I_K < I_K^*$ , it is called under-running. In either case, the spending function is adjusted to accommodate the inequality, by redefining

$$I_K^* = I_K$$

See the discussion in Wassmer and Brannath (2016), pages 78-79, or Jennison and Turnbull (2000), pages 153-154, 162.

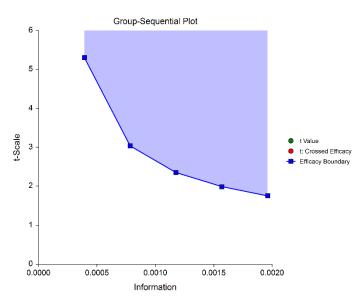
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# **Types of Boundaries**

A variety of boundary designs are available to reflect the needs of the study design.

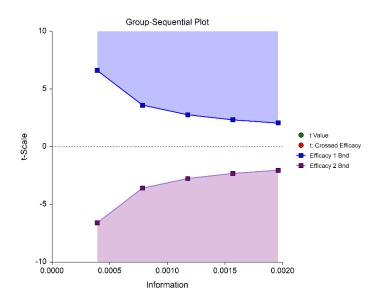
#### Efficacy Only (One-Sided)

The simplest group-sequential test involves a single set of stage boundaries with early stopping for efficacy.



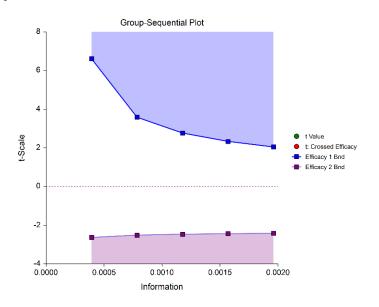
#### Efficacy Only (Two-Sided, Symmetric)

This boundary type would be used if the goal is to compare treatments, and it is not known in advance which treatment should be better.



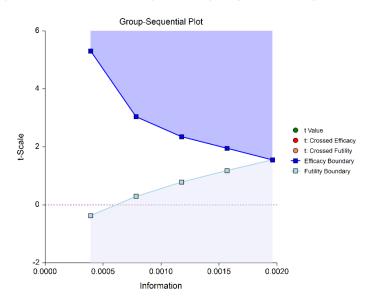
#### Efficacy 1 and Efficacy 2 / Harm (Two-Sided, Asymmetric)

These boundaries might be used to show efficacy on one side or harm on the other side. This design might be used in place of a one-sided efficacy and futility design if showing harm has additional benefit over stopping early for futility.



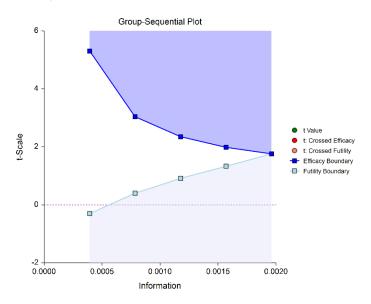
#### Efficacy and Binding Futility (One-Sided)

This design allows early stopping for either efficacy or futility. For binding futility designs, the Type I error protection (alpha) is only maintained if the study is strictly required to stop if either boundary is crossed.



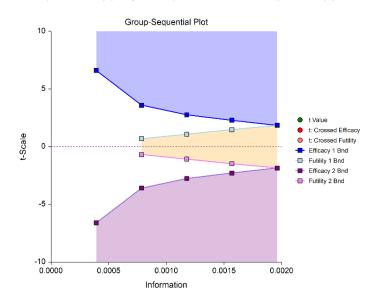
#### Efficacy and Non-Binding Futility (One-Sided)

This design also allows early stopping for either efficacy or futility. For non-binding futility designs, the Type I error protection (alpha) is maintained, regardless of whether the study continues after crossing a futility boundary. However, the effect is to make the test conservative (alpha is lower than the stated alpha and power is lower than the stated power).



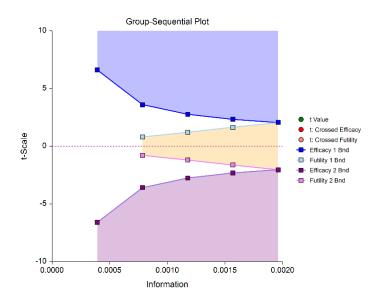
#### Efficacy and Binding Futility (Two-Sided, Symmetric)

This design allows early stopping for either efficacy or futility on either side. Alpha is preserved only if crossing of futility boundaries strictly leads to early stopping for futility. In early looks of this design, the futility boundaries may overlap. Overlapping futility boundaries may be skipped or left as they are.



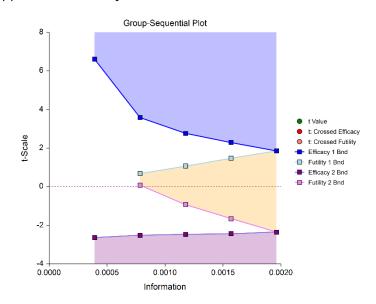
#### Efficacy and Non-Binding Futility (Two-Sided, Symmetric)

This design allows early stopping for either efficacy or futility on either side. Alpha is preserved even when the study is allowed to continue after crossing a futility boundary. In early looks of this design, the futility boundaries may overlap. Overlapping futility boundaries may be skipped or left as they are.



#### Efficacy 1, Efficacy 2 / Harm, and Binding Futility (Two-Sided, Asymmetric)

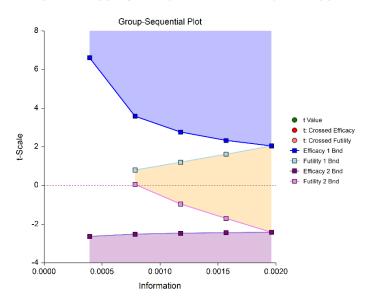
This design allows early stopping for efficacy and efficacy futility, and for harm and harm futility (or efficacy 2 and efficacy 2 futility). Binding futility boundaries require that the study is stopped when a binding futility boundary is crossed. In early looks of this design, the futility boundaries may overlap. Overlapping futility boundaries may be skipped or left as they are.



#### Group-Sequential T-Tests for One Mean (Simulation)

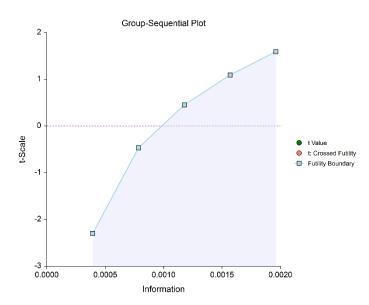
#### Efficacy 1, Efficacy 2 / Harm, and Non-Binding Futility (Two-Sided, Asymmetric)

This design allows early stopping for efficacy and efficacy futility, and for harm and harm futility (or efficacy 2 and efficacy 2 futility). Non-binding futility boundaries do not require that the study is stopped when a binding futility boundary is crossed, but the study design is conservative. In early looks of this design, the futility boundaries may overlap. Overlapping futility boundaries may be skipped or left as they are.



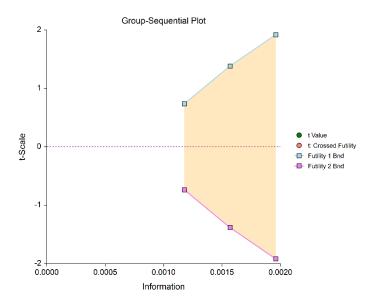
#### Futility Only (One-Sided)

In this design, the interim analyses are used only for futility. Please be aware that, due to computational complexity, these boundaries may take several minutes to compute, particularly when some stages are skipped.



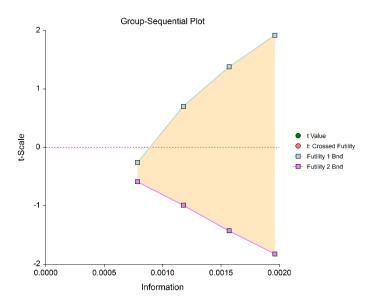
#### Futility Only (Two-Sided, Symmetric)

In this design, the study is stopped early only for futility. Overlapping futility boundaries may be skipped or left as they are. Please be aware that, due to computational complexity, these boundaries may take several minutes to compute, particularly when overlapping boundaries are removed or some stages are skipped.



#### Futility Only (Two-Sided, Asymmetric)

In this design, all stages previous to the final stage are used only for futility. Overlapping futility boundaries may be skipped or left as they are. Please be aware that, due to computational complexity, these boundaries may take several minutes to compute, particularly when overlapping boundaries are removed or some stages are skipped.



## **Boundary Calculations**

The foundation of the spending function approach used in this procedure is given in Lan & DeMets (1983). This procedure implements the methods given in Reboussin, DeMets, Kim, & Lan (1992) to calculate the boundaries and stopping probabilities of the various group sequential designs. Some adjustments are made to these methods to facilitate the calculation of futility boundaries.

#### **Obtaining t-scale Boundaries from Z-scale Boundaries**

The methodology underlying all boundary calculations is based on *Z*-boundary calculations. Following the recommendation of Jennison and Turnbull (2000), p. 80, *Z*-scale boundaries are first produced, using the common methods. The corresponding *p*-value boundaries are computed from the *Z*-value boundaries. These *p*-value boundaries are then converted to *t*-value boundaries, using the appropriate degrees of freedom. As discussed in Jennison and Turnbull (2000), these *t*-value boundaries have been found to be 'remarkably accurate.'

# **Binding vs. Non-Binding Futility Boundaries**

Futility boundaries are used to facilitate the early stopping of studies when early evidence leans to lack of efficacy. When binding futility boundaries are to be used, the calculation of the futility and efficacy boundaries assumes that the study will be strictly stopped at any stage where a futility or efficacy boundary is crossed. If strict adherence is not maintained, then the Type I and Type II error probabilities associated with the boundaries are no longer valid. One (perhaps undesirable) effect of using binding futility boundaries is that the resulting final stage boundary may be lower than the boundary given in the corresponding fixed-sample design.

When non-binding futility boundaries are calculated, the efficacy boundaries are first calculated ignoring futility boundaries completely. This is done so that alpha may be maintained whether or not a study continues after crossing a futility boundary. One (perhaps undesirable) effect of using non-binding futility boundaries is that the overall group-sequential test becomes conservative (alpha is lower than the stated alpha and power is lower than the stated power).

# **Spending Functions**

Spending functions are used to distribute portions of alpha (or beta) to the stages according to the proportion of accumulated information at each look.

#### **Spending Function Characteristics**

• Spending functions give a value of zero when the proportion of accumulated information is zero.

 $\alpha(0) = 0$  (for alpha-spending)

 $\beta(0) = 0$  (for beta-spending)

• Spending functions are increasing functions.

• Spending functions give a value of alpha (or beta) when the proportion of accumulated information is one.

 $\alpha(1) = \alpha$  (for alpha-spending)  $\beta(1) = \beta$  (for beta-spending)

Using spending functions in group-sequential analyses is very flexible in that neither the information proportions nor the number of stages need be specified in advance to maintain Type I and Type II error protection.

#### Spending Functions Available in this Procedure

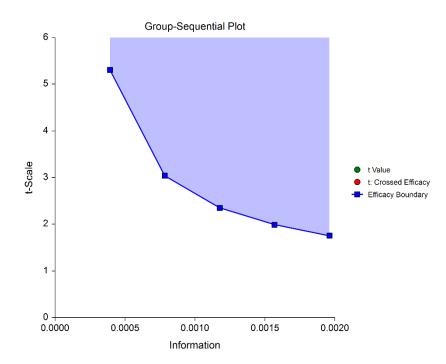
The following spending functions are shown as alpha-spending functions. The corresponding beta-spending function is given by replacing  $\alpha$  with  $\beta$ .

#### O'Brien-Fleming Analog

The O'Brien Fleming Analog (Lan & DeMets, 1983) roughly mimics the O'Brien-Fleming (non-spending function) design, with the key attribute that only a small proportion of alpha is spent early. Its popularity comes from it proportioning enough alpha to the final stage that the final stage boundary is not too different from the fixed-sample (non-group-sequential) boundary.

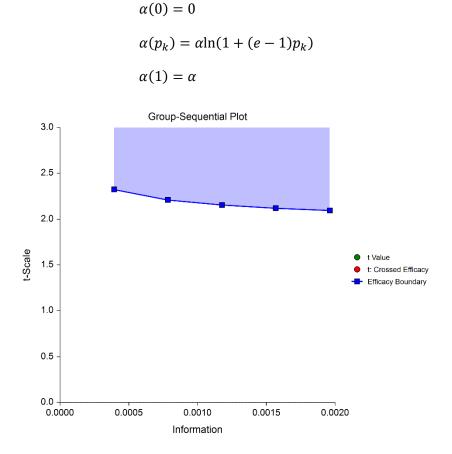
$$\alpha(0) = 0$$
  
$$\alpha(p_k) = 2 - 2\Phi\left(\frac{Z_{1-\alpha/2}}{\sqrt{p_k}}\right)$$

 $\alpha(1) = \alpha$ 



#### **Pocock Analog**

The Pocock Analog (Lan & DeMets, 1983) roughly mimics the Pocock (non-spending function) design, with the key attribute that alpha is spent roughly equally across all stages.



#### **Power Family**

The power family of spending functions has a  $\rho$  parameter that gives flexibility in the spending function shape.

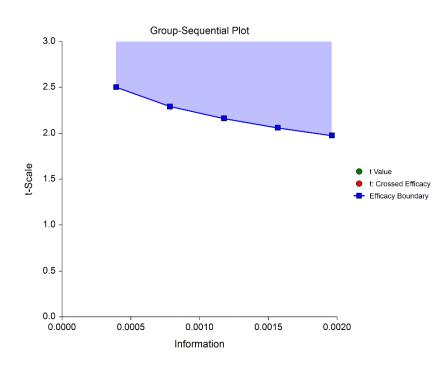
$$\alpha(0) = 0$$
  

$$\alpha(p_k) = p_k^{\rho}, \ \rho > 0$$
  

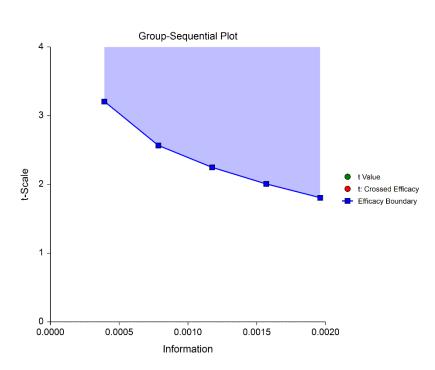
$$\alpha(1) = \alpha$$

A power family spending function with a  $\rho$  of 1 is similar to a Pocock design, while a power family spending function with a  $\rho$  of 3 is more similar to an O'Brien-Fleming design.

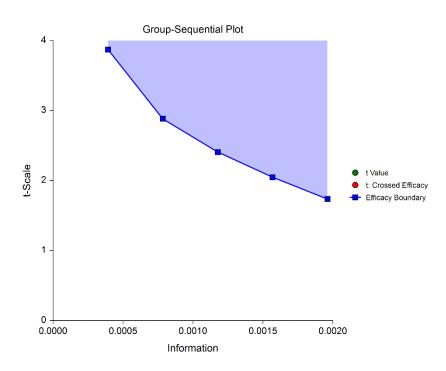
$$\rho = 1$$



 $\rho = 2$ 



 $\rho = 3$ 



#### Hwang-Shih-DeCani (Gamma Family)

The Hwang-Shih-DeCani gamma family of spending function has a  $\gamma$  parameter that allows for a variety of spending functions.

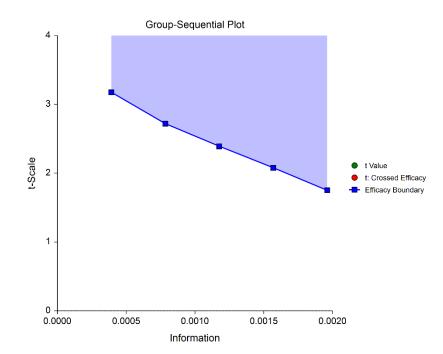
$$\alpha(0) = 0$$
  

$$\alpha(p_k) = \alpha \left(\frac{1 - e^{-\gamma p_k}}{1 - e^{-\gamma}}\right), \ \gamma \neq 0$$
  

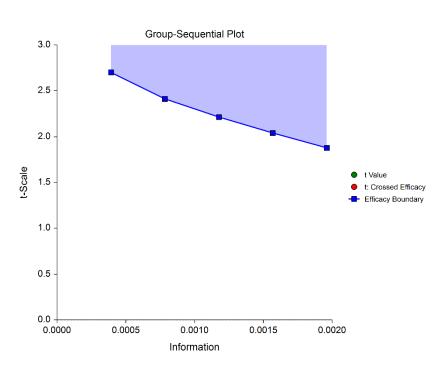
$$\alpha(p_k) = \alpha p_k, \ \gamma = 0$$
  

$$\alpha(1) = \alpha$$

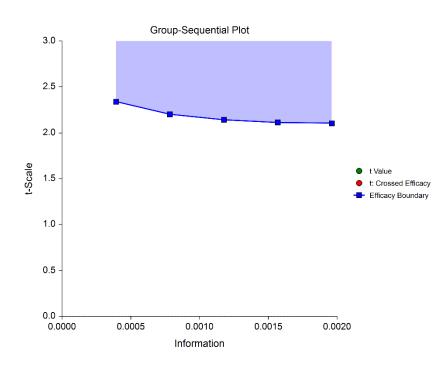
 $\gamma = -3$ 



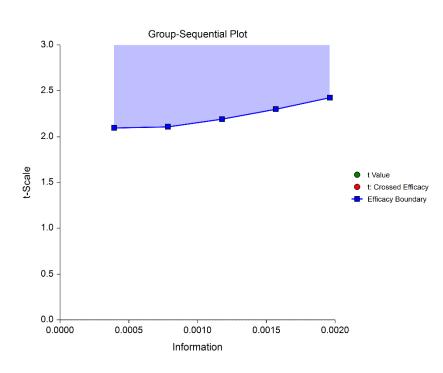
 $\gamma = -1$ 



 $\gamma = 1$ 



 $\gamma = 3$ 



# Using Simulation to obtain Boundary Crossing Probabilities

In addition to providing an overall estimate of power, it can be useful to researchers to know the probability of crossing each of the group-sequential boundaries, given a specified assumed value for the means. The following steps are used to estimate these probabilities using simulation:

- 1. Determine the target (cumulative) sample size for each stage, including the final stage. Fractional sample sizes are rounded up to the next integer.
- 2. For each simulation, obtain a simulated data set with the final stage sample size. Simulated values are generated from a Normal distribution with user-specified mean and planning (for Stage 0) or current standard deviation.
- 3. Determine whether simulation *t*-values are 'held out' after crossing a boundary, or whether simulation *t*-values are 'left in' (compared to boundaries at all future stages, regardless of whether a boundary was crossed at a previous stage).
  - a. If simulation *t*-values are 'held out' after crossing a boundary, it is determined for each simulation which boundary was crossed first (except in the case of non-binding futility boundaries).
  - b. If simulation *t*-values are 'left in' after crossing a boundary, it is determined for each simulation all the boundaries where the *t*-value is across the boundary.
- 4. The proportion of simulations crossing each boundary provides an estimate of the probability of crossing each boundary, given the specified assumed mean.

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#### Group-Sequential T-Tests for One Mean (Simulation)

- 5. Overall power and alpha calculations are also based on the specification of 'held out' or 'left in'.
  - a. When Hold Out is selected, power and alpha are calculated as the sum of all efficacy boundary proportions.
  - b. When Leave In is selected, power and alpha are calculated as the efficacy boundary proportion of the final stage.

#### **Non-binding Futility Boundaries**

When non-binding futility boundaries are used, the study may continue when a futility boundary is crossed. The simulation proportions will have a slightly different interpretation when this is the case.

# Example 1 – Sample Size and Initial Boundaries for a Group-Sequential T-Test

[Please note that this example has a calculation time of several minutes.]

A blood pressure treatment study is conducted to determine whether a new drug results in lower patient blood pressure than a current standard mean of 125. The response for each patient is a resting systolic blood pressure. A one-sided test with alpha equal to 0.025 is used.

The null and alternative hypotheses are

$$H_0: \mu - \mu_0 = 0 \quad (H_0: \mu_{New} = 125)$$

versus

 $H_a: \mu - \mu_0 < 0 \quad (H_a: \mu_{New} < 125)$ 

The design calls for five equally spaced stages if the final stage is reached. A power of 0.90 is needed. The standard deviation is expected to be 25. Researchers wish to examine the sample sizes needed for new treatment means of 116, 118, and 120. Both efficacy and non-binding futility boundaries are intended. The efficacy (alpha-spending) spending function used is the O'Brien-Fleming analog. The Hwang-Shih-DeCani (Gamma) beta-spending function with gamma parameter 1.5 is used for futility.

#### Setup

If the procedure window is not already open, use the PASS Home window to open it. The parameters for this example are listed below and are stored in the **Example 1** settings file. To load these settings to the procedure window, click **Open Example Settings File** in the Help Center or File menu.

sigr	

Solve For	
Power	-
Alpha	
μ	
μ0	
σ	
Maximum Number of Stages (K)	5
Info. Proportion at each Stage	Equally incremented
Boundaries Used	
Hypothesis Direction	Ηa: μ - μ0 < 0
	Spending Function Calculation
Alpha Spending Function	O'Brien-Fleming Analog
Skipped Efficacy Stages	<empty></empty>
Design Beta	0.10
Beta Spending Function	Hwang-Shih-DeCani (γ)
γ	
Skipped Futility Stages	
Binding or Non-Binding Futility	Non-Binding

#### Group-Sequential T-Tests for One Mean (Simulation)

Options Tab	
Number of Simulations	
Random Seed	
After Boundary Crossing	Hold out
Boundary Reports Tab	
All Reports	Checked
Boundary Plots Tab	
t-Statistic vs Information	Checked
t-Statistic vs Stage	Checked
t-Statistic vs N	Checked
Summary Reports Tab	
All Reports	Checked
Summary Plots Tab	
All plots	<b>Checked</b> (only 2D will be used)

# Output

Click the Calculate button to perform the calculations and generate the following output. This run will take several minutes to an hour (the number of simulations could be lowered, but the variation in results will be greater). The simulation results will differ slightly for each separate run.

#### **Run Summary Report – Scenario 1**

This report can be used to confirm that the input was processed as intended.

#### **Run Summary Report - Scenario 1**

Item	Value
Solve For	Sample Size
Maximum Number of Stages (Design)	5
Current Stage	0
Alternative Hypothesis	μ - μ0 < 0 (one-sided)
Alpha Spending Function	O'Brien-Fleming Analog
Beta Spending Function	Hwang-Shih-DeCani (γ = 1.5)
Futility Boundaries	Non-Binding
Target Alpha	0.025
Alpha (from simulations)	0.03
μ	116
μΟ	125
σ	25
N (if final stage reached)	85
Target Power	0.9
Power (from simulations)	0.911
Maximum Information	0.136

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#### t-Value Boundaries

This section gives the planning stage t-statistic boundaries, numerically. These values are reflected in the group-sequential boundary plot.

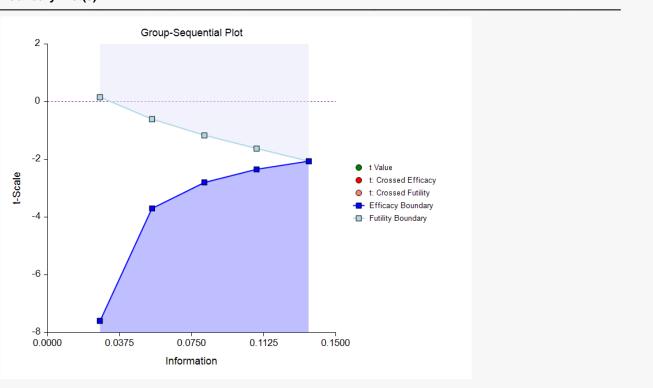
#### t-Value Boundaries

Alternati	n Information: 0.136 ve Hypothesis: μ - μ0 < 0 (one-sided) oundaries: Non-Binding		
			Information
Stage	Efficacy	Futility	Proportion
1	-7.5967	0.1559	0.2
2	-3.6970	-0.6044	0.4
3	-2.7943	-1.1678	0.6
4	-2.3443	-1.6227	0.8
5	-2.0624	-2.0624	1.0

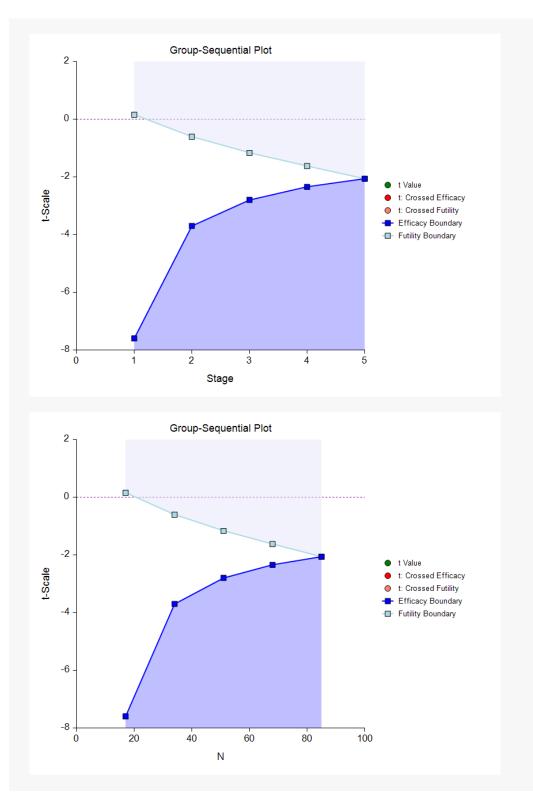
#### Boundary Plot(s)

This plot shows the efficacy and futility t-statistic planning boundaries. It is anticipated that these boundaries will adjust to the actual information proportions as the data for each stage is realized.

#### Boundary Plot(s)



#### Group-Sequential T-Tests for One Mean (Simulation)



#### P-Value Boundaries

This section reflects the conversion of the Z-value boundaries to the corresponding P-value boundaries.

#### **P-Value Boundaries**

Maximum Information:	0.136
Alternative Hypothesis:	$\mu - \mu 0 < 0$ (one-sided)
Futility Boundaries:	Non-Binding
P-value boundaries are o	one-sided values.

	Bound	daries	Information
Stage	Efficacy	Futility	Proportion
1	0.00000	0.56095	0.2
2	0.00039	0.27484	0.4
3	0.00368	0.12421	0.6
4	0.01102	0.05468	0.8
5	0.02113	0.02113	1.0

### **Underlying Z Scale Boundaries**

This section reflects the Z-value boundaries from which the t-value boundaries were derived.

#### **Underlying Z Scale Boundaries**

Alternativ	um Information: 0.136 tive Hypothesis: μ - μ0 < 0 (o Boundaries: Non-Binding		) (one-sided) ling
	Boundaries		Information
Stage	Efficacy	Futility	Proportion
1	-4.8769	0.1534	0.2
2	-3.3569	-0.5982	0.4
3	-2.6803	-1.1542	0.6
4	-2.2898	-1.6011	0.8
5	-2.0310	-2.0310	1.0

#### **Information Report**

This section gives the target information for each stage, as well as the sample sizes and standard deviations used to calculate those informations.

#### Information Report

	n Information: ve Hypothesis:	0.136 μ - μ0 < 0 (one-sic 0.025	led)		
Stage	Target Information Proportion	Target Information	Target Sample Size N	σ	df
1	0.2	0.0272	17	25	16
2	0.4	0.0544	34	25	33
3	0.6	0.0816	51	25	50
4	0.8	0.1088	68	25	67
5	1.0	0.1360	85	25	84

#### Alpha Spending

This section shows how alpha is anticipated to be spent across the stages.

#### **Alpha Spending**

	Final Stage Alpha: Ig Function:	0.025 O'Brien-Flemin	g Analog			
Stage	Information Proportion	Alpha Spent this Stage	Cumulative Alpha Spent	Nominal (Boundary) Alpha	Percentage Alpha Spent this Stage	Cumulative Percentage Alpha Spent
1 *	0.2	0.0000	0.0000	0.000001	0.0	0.0
2 *	0.4	0.0004	0.0004	0.000394	1.6	1.6
3 *	0.6	0.0034	0.0038	0.003678	13.7	15.2
4 *	0.8	0.0084	0.0122	0.011017	33.6	48.8
5 *	1.0	0.0128	0.0250	0.021128	51.2	100.0

\* projected

## Beta Spending for Futility

This section shows how beta is anticipated to be spent across the stages.

#### **Beta Spending for Futility**

•	Cumulative Beta a g Function for Fut	-	.1 Iwang-Shih-DeCa	ni (γ = 1.5)		
Stage	Information Proportion	Beta Spent this Stage	Cumulative Beta Spent	Nominal (Boundary) Beta	Percentage Beta Spent this Stage	Cumulative Percentage Beta Spent
1 *	0.2	0.0334	0.0334	0.560952	33.4	33.4
2 *	0.4	0.0247	0.0581	0.274840	24.7	58.1
3 *	0.6	0.0183	0.0764	0.124207	18.3	76.4
4 *	0.8	0.0136	0.0900	0.054676	13.6	90.0
5 *	1.0	0.0100	0.1000	0.021128	10.0	100.0

\* projected

#### Boundary Probabilities for $\delta = -9$

Using simulation based on the specified means and standard deviation, this section gives the estimated probabilities of crossing each of the boundaries. Values given here will vary for each simulation.

#### Boundary Probabilities for $\delta = -9$

Number of Simulations: Random Seed: Futility Boundaries: After Efficacy Boundary Crossing: After Non-Binding Futility Boundary Crossing: Alternative Hypothesis: μ: μ0: δ: σ: Efficacy		1000 2310555 (User-Entered) Non-Binding Hold Out Leave In $\mu - \mu 0 < 0$ (one-sided) 116 125 -9 25			
		Effi	сасу	Fu	tility
Stage	Ν	Boundary	Probability	Boundary	Probability
1	*17	-7.5967	0.000	0.1559	0.049
2	*34	-3.6970	0.079	-0.6044	0.063
3	*51	-2.7943	0.374	-1.1678	0.071
4	*68	-2.3443	0.305	-1.6227	0.085
•		2.0110			0.000

\* Simulation sample size (Non-integer sample sizes were rounded to the next highest integer.)

Average N: 63.07

## Boundary Probabilities for $\delta = 0$ (Alpha)

This section estimates the probabilities of crossing each boundary if the difference for the remaining stages is assumed to be zero.

#### Boundary Probabilities for $\delta = 0$ (Alpha)

Efficacy	Futility
σ:	25
δ:	0
μ0:	125
μ:	125
Alternative Hypothesis:	μ - μ0 < 0 (one-sided)
After Non-Binding Futility Boundary Crossing:	Leave In
After Efficacy Boundary Crossing:	Hold Out
Futility Boundaries:	Non-Binding
Random Seed:	2310555 (User-Entered)
Number of Simulations:	1000

		L	leacy	T durinty		
Stage	Ν	Boundary	Probability	Boundary	Probability	
1	*17	-7.5967	0.000	0.1559	0.420	
2	*34	-3.6970	0.002	-0.6044	0.703	
3	*51	-2.7943	0.002	-1.1678	0.867	
4	*68	-2.3443	0.012	-1.6227	0.937	
5	*85	-2.0624	0.014	-2.0624	0.976	

\* Simulation sample size (Non-integer sample sizes were rounded to the next highest integer.)

Average N: 84.626

#### Scenario 2

All of the same boundary reports are given for Scenario 2, corresponding to a  $\mu$  value of 118.

#### Scenario 3

All of the same boundary reports are given for Scenario 3, corresponding to a  $\mu$  value of 120.

#### Power and Sample Size Summary

#### Power and Sample Size Summary

Alternativ Alpha Sp Beta Spe	n Number of ve Hypothes bending Func- ending Func- of Simulation	is: ction: tion:	μ - μ0 O'Briei Hwang 1000	e Size < 0 (one- n-Flemin g-Shih-De 55 (User-	g Anaĺo eCani (γ	v = 1.5)	
Target Power	Sim Power	N	μ	μ0	σ	Target Alpha	Sim Alpha
0.9	0.911	85	116	125	25	0.025	0.030
0.9	0.910	139	118	125	25	0.025	0.019

0.9	0.910	279	120	125	25	0.025	0.028
Target Powe Sim Power	The pr	oportion o	f simulatio	n t-values	that cros	,	re. boundary. Because "After Boundary Crossing" is rossing proportions.
N	The ar	ticipated t	otal numb	er of indiv	iduals if tl	ne final stage	is reached.
μ	The as	sumed me	ean of the	populatio	n for powe	er calculation	simulations.
μO		Ill hypothe lations.	sized mea	n. µ0 is a	lso the as	sumed mean	of the population for alpha calculation
σ		sumed po mum infor		andard d	eviation. c	σ is used for s	imulating values as well as for the calculation of
Target Alpha Sim Alpha	The pr	oportion o	f null simu	ation t-va	lues that	cross an effica	desired overall probability of a Type 1 error. acy boundary. Because "After Boundary Crossing" / crossing proportions.

#### Summary Statements

A single-group group-sequential design with a maximum of 5 stages will be used to test whether the mean is less than the null mean 125 (H0:  $\mu \ge 125$  versus H1:  $\mu < 125$ ). The comparison will be made at each stage using a one-sample t-test, with efficacy and futility boundary values calculated from the designated spending functions. The target cumulative Type I error rate ( $\alpha$ ) at the final stage is 0.025. The standard deviation is assumed to be 25. To detect a mean of 116 (difference of -9) with 90% power, the number of needed subjects at the final stage will be 85.

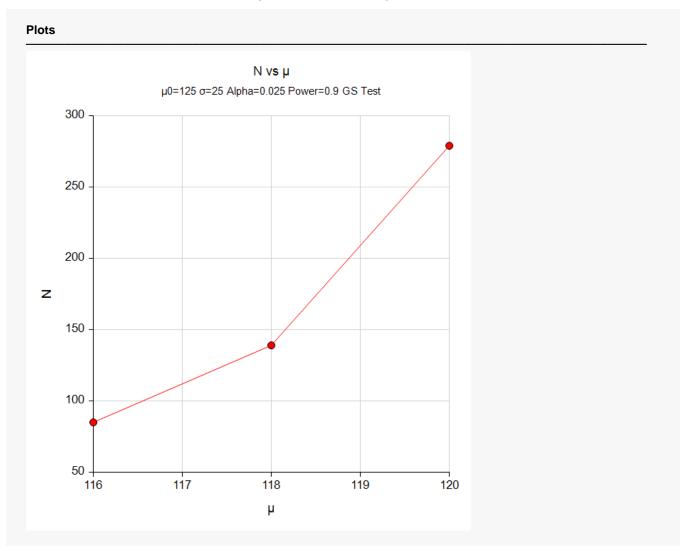
#### References

- Jennison, C. and Turnbull, B.W. 2000. Group Sequential Methods with Applications to Clinical Trials. Chapman and Hall/CRC. Boca Raton.
- Lan, K.K.G. and DeMets, D.L. 1983. 'Discrete sequential boundaries for clinical trials.' Biometrika, 70, pages 659-663.
- Reboussin, D.M., DeMets, D.L., Kim, K., and Lan, K.K.G. 1992. 'Programs for computing group sequential boundaries using the Lan-DeMets Method.' Technical Report 60, Department of Biostatistics, University of Wisconsin-Madison.

This report shows the values of each of the parameters, one scenario per row. The values may vary slightly due to the variation in simulations. The details for each of the rows of this report are given in the earlier boundary reports.

The values from this table are exhibited in the plot below.

# Plots Section for Power and Sample Size Summary



# **Example 2 – Skipping Stage Boundaries**

[Please note that this example has a calculation time of several minutes.]

Suppose that the scenario is exactly as in Example 1, except that the first two futility boundaries are to be skipped.

#### Setup

If the procedure window is not already open, use the PASS Home window to open it. The parameters for this example are listed below and are stored in the **Example 2** settings file. To load these settings to the procedure window, click **Open Example Settings File** in the Help Center or File menu.

Design Tab	
Solve For	Sample Size
Power	0.90
Alpha	0.025
μ	116 118 120
μ0	125
σ	25
Maximum Number of Stages (K)	5
Info. Proportion at each Stage	Equally incremented
Boundaries Used	One-sided Efficacy with Futility
Hypothesis Direction	Ηa: μ - μ0 < 0
Boundary Specification	Spending Function Calculation
Alpha Spending Function	O'Brien-Fleming Analog
Skipped Efficacy Stages	<empty></empty>
Design Beta	0.10
Beta Spending Function	Hwang-Shih-DeCani (γ)
γ	1.5
Skipped Futility Stages	
Binding or Non-Binding Futility	Non-Binding
Options Tab	
Number of Simulations	
Random Seed	
After Boundary Crossing	Hold out
Boundary Reports Tab	
Boundary Reports Tab All Reports	Checked
	Checked
All Reports	
All Reports Boundary Plots Tab	Checked

Summary Reports Tab	
All Reports	Checked
Summary Plots Tab	
All plots	<b>Checked</b> (only 2D will be used)

# Output

Click the Calculate button to perform the calculations and generate the following output. This run will take several minutes to an hour (the number of simulations could be lowered, but the variation in results will be greater). The simulation results will differ slightly for each separate run.

### **Run Summary Report**

#### **Run Summary Report - Scenario 1**

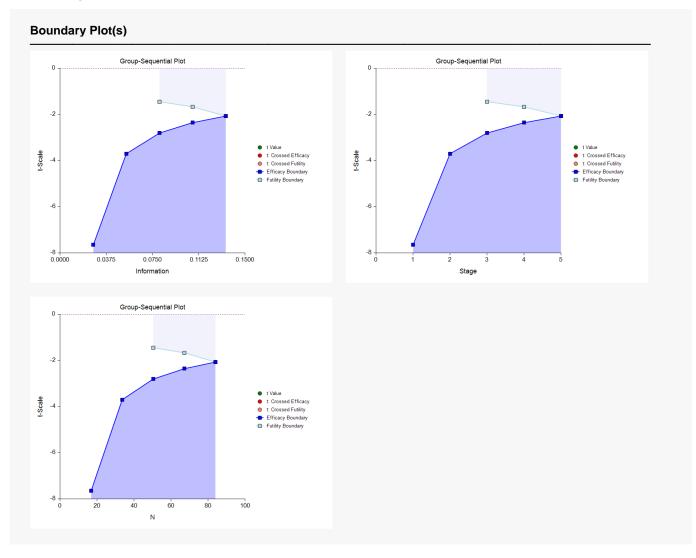
Item	Value
Solve For	Sample Size
Maximum Number of Stages (Design)	5
Skipped Futility Stage(s)	12
Current Stage	0
Alternative Hypothesis	μ - μ0 < 0 (one-sided)
Alpha Spending Function	O'Brien-Fleming Analog
Beta Spending Function	Hwang-Shih-DeCani ( $\gamma = 1.5$ )
Futility Boundaries	Non-Binding
Target Alpha	0.025
Alpha (from simulations)	0.023
μ	116
μΟ	125
σ	25
N (if final stage reached)	84
Target Power	0.9
Power (from simulations)	0.913
Maximum Information	0.1344

# t-Value Boundaries

### t-Value Boundaries

Alternati	m Information: ve Hypothesis Boundaries:		) (one-sided) ling
Boundaries		Information	
Stage	Efficacy	Futility	Information Proportion
1	-7.6448		0.2
2	-3.7015		0.4
3	-2.7957	-1.4454	0.6
4	-2.3450	-1.6676	0.8
5	-2.0628	-2.0628	1.0

# **Boundary Plot(s)**



# **P-Value Boundaries**

### **P-Value Boundaries**

	Bound	daries	Information
Stage	Efficacy	Futility	Information Proportion
1	0.00000		0.2
2	0.00039		0.4
3	0.00368	0.07733	0.6
4	0.01102	0.05006	0.8
5	0.02113	0.02113	1.0

# Underlying Z Scale Boundaries

### Underlying Z Scale Boundaries

Maximum Information: Alternative Hypothesis: Futility Boundaries:	$\mu - \mu 0 < 0$ (one-sided)
Bounda	ries Information

Stage	Efficacy	Futility	Proportion
1	-4.8769		0.2
2	-3.3569		0.4
3	-2.6803	-1.4232	0.6
4	-2.2898	-1.6443	0.8
5	-2.0310	-2.0310	1.0

# **Information Report**

#### Information Report

	n Information: /e Hypothesis:	0.1344 μ - μ0 < 0 (one-sic 0.025	led)		
Stage	Target Information Proportion	Target Information	Target Sample Size N	σ	df
1	0.2	0.0269	16.8	25	15.8
2	0.4	0.0538	33.6	25	32.6
3	0.6	0.0806	50.4	25	49.4
4	0.8	0.1075	67.2	25	66.2
5	1.0	0.1344	84.0	25	83.0

# Alpha Spending

Target Final Stage Alpha: Spending Function:		0.025 O'Brien-Flemin	g Analog			
Stage	Information Proportion	Alpha Spent this Stage	Cumulative Alpha Spent	Nominal (Boundary) Alpha	Percentage Alpha Spent this Stage	Cumulative Percentage Alpha Spent
1 *	0.2	0.0000	0.0000	0.000001	0.0	0.0
2 *	0.4	0.0004	0.0004	0.000394	1.6	1.6
3 *	0.6	0.0034	0.0038	0.003678	13.7	15.2
4 *	0.8	0.0084	0.0122	0.011017	33.6	48.8
5 *	1.0	0.0128	0.0250	0.021128	51.2	100.0

\* projected

# Beta Spending for Futility

#### Beta Spending for Futility

Target Cumulative Beta at Final Stage:	0.1
Spending Function for Futility:	Hwang-Shih-DeCani (γ = 1.5)

Stage	Information Proportion	Beta Spent this Stage	Cumulative Beta Spent	Nominal (Boundary) Beta	Percentage Beta Spent this Stage	Cumulative Percentage Beta Spent
1 *	0.2	0.0000	0.0000	1.000000	0.0	0.0
2 *	0.4	0.0000	0.0000	1.000000	0.0	0.0
3 *	0.6	0.0764	0.0764	0.077334	76.4	76.4
4 *	0.8	0.0136	0.0900	0.050056	13.6	90.0
5 *	1.0	0.0100	0.1000	0.021128	10.0	100.0

\* projected

# Boundary Probabilities for $\delta = -9$

#### Boundary Probabilities for $\delta = -9$

Number of Simulations:	1000
Random Seed:	2033118 (User-Entered)
Futility Boundaries:	Non-Binding
After Efficacy Boundary Crossing:	Hold Out
After Non-Binding Futility Boundary Crossing:	Leave In
Alternative Hypothesis:	μ - μ0 < 0 (one-sided)
μ:	116
μ0:	125
δ:	-9
σ:	25

		Effi	сасу	Fu	tility
Stage	Ν	Boundary	Probability	Boundary	Probability
1	*16.8	-7.6448	0.000		0.000
2	*33.6	-3.7015	0.071		0.000
3	*50.4	-2.7957	0.342	-1.4454	0.120
4	*67.2	-2.3450	0.356	-1.6676	0.083
5	*84.0	-2.0628	0.144	-2.0628	0.094

\* Simulation sample size (Non-integer sample sizes were rounded to the next highest integer.)

Average N: 62.9496

### Boundary Probabilities for $\delta = 0$ (Alpha)

#### Boundary Probabilities for $\delta = 0$ (Alpha)

Number of Simulations:	1000
Random Seed:	2033118 (User-Entered)
Futility Boundaries:	Non-Binding
After Efficacy Boundary Crossing:	Hold Out
After Non-Binding Futility Boundary Crossing:	Leave In
Alternative Hypothesis:	$\mu - \mu 0 < 0$ (one-sided)
μ:	125
μ0:	125
δ:	0
σ:	25

	Effi	icacy	Fu	tility
Ν	Boundary	Probability	Boundary	Probability
*16.8	-7.6448	0.000	· · · · · · · · · · · · · · · · · · ·	0.000
*33.6	-3.7015	0.001		0.000
*50.4	-2.7957	0.003	-1.4454	0.919
*67.2	-2.3450	0.009	-1.6676	0.952
*84.0	-2.0628	0.010	-2.0628	0.982
	*16.8 *33.6 *50.4 *67.2	N         Boundary           *16.8         -7.6448           *33.6         -3.7015           *50.4         -2.7957           *67.2         -2.3450	*16.8 -7.6448 0.000 *33.6 -3.7015 0.001 *50.4 -2.7957 0.003 *67.2 -2.3450 0.009	N         Boundary         Probability         Boundary           *16.8         -7.6448         0.000         *33.6         -3.7015         0.001           *50.4         -2.7957         0.003         -1.4454           *67.2         -2.3450         0.009         -1.6676

\* Simulation sample size (Non-integer sample sizes were rounded to the next highest integer.)

Average N: 83.6976

### Scenario 2

All of the same boundary reports are given for Scenario 2, corresponding to a  $\mu$  value of 118.

### Scenario 3

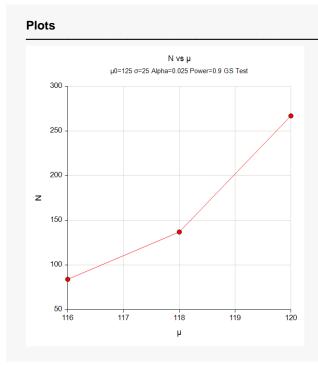
All of the same boundary reports are given for Scenario 3, corresponding to a  $\mu$  value of 120.

# Power and Sample Size Summary

Solve Fo	or:		Sample	e Size				
Maximur	m Number of	Stages:	5					
	Futility Stag	0	12					
	ve Hypothes		μ - μ0 ·	< 0 (one-	sided)			
	pending Fun		O'Brier	n-Flèming	g Analog	3		
	ending Func			-Shih-De				
•								
Number	of Simulatio	ns:	1000			,		
Number Random		ns:		8 (User-	Entered	l)		
		ns:		8 (User-	Entered	Target	Sim	
Random	Seed:	ns: N		l8 (User- μ0	Enterec <b>o</b>		Sim Alpha	
Random Target	Seed:		20331			Target		
Random Target Power	Seed: Sim Power	N	20331 <sup>2</sup> µ	μ0	σ	Target Alpha	Alpha	

This report shows little change in overall sample size, with the difference possibly due to simulation variability.

### Plots Section for Power and Sample Size Summary



# **Example 3 – Finding Power**

[Please note that this example has a calculation time of several minutes.]

Suppose that the scenario is similar to the setup of Example 1, except that now we will solve for power for various sample sizes of 60, 80, 100, 120, and 140.

## Setup

If the procedure window is not already open, use the PASS Home window to open it. The parameters for this example are listed below and are stored in the **Example 3** settings file. To load these settings to the procedure window, click **Open Example Settings File** in the Help Center or File menu.

Design Tab	
Solve For	Power
Alpha	0.025
N	60 80 100 120 140
μ	
μ0	
σ	
Maximum Number of Stages (K)	5
Info. Proportion at each Stage	Equally incremented
Boundaries Used	One-sided Efficacy with Futility
Hypothesis Direction	Ηa: μ - μ0 < 0
Boundary Specification	Spending Function Calculation
Alpha Spending Function	O'Brien-Fleming Analog
Skipped Efficacy Stages	<empty></empty>
Design Beta	0.10
Beta Spending Function	Hwang-Shih-DeCani (γ)
γ	1.5
Skipped Futility Stages	<empty></empty>
Binding or Non-Binding Futility	Non-Binding
Options Tab	
Number of Simulations	
	are recommended)
After Boundary Crossing	Hold out
Boundary Reports Tab	
All Reports	Checked
Boundary Plots Tab	
t-Statistic vs Information	Chacked
t-Statistic vs Stage	Chacked

Summary Reports Tab		
All Reports	Checked	
Summary Plots Tab		
All plots	Checked	

# Output

Click the Calculate button to perform the calculations and generate the following output. This run will take several minutes to an hour (the number of simulations could be lowered, but the variation in results will be greater). The simulation results will differ slightly for each separate run.

### **Scenario Reports**

All of the scenario reports for each of the 15 scenarios are generated in the output, but they are not shown here.

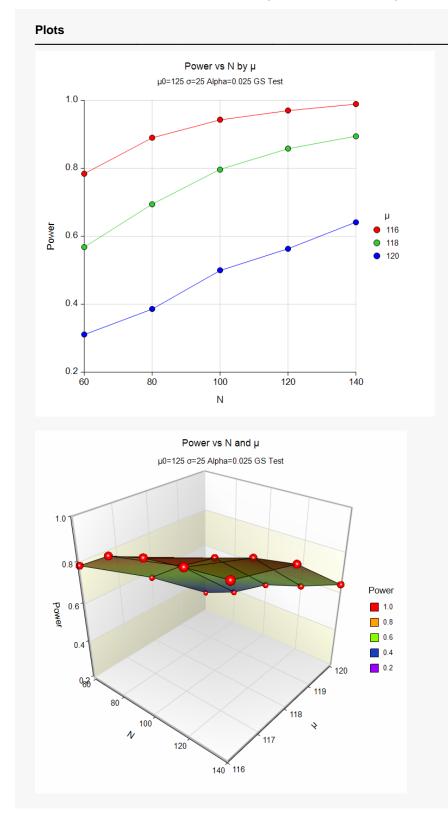
## Power and Sample Size Summary

This summary is shown near the bottom of the output. The navigation pane may be useful to find it quickly.

#### Power and Sample Size Summary

Solve For Maximum Alternativ Alpha Sp Beta Spe Number of Random	n Numbe re Hypotl ending Funding Fundi	nesis: function: inction:	μ - Ο'Β Ηw 100	µ0 < 0 ( Brien-Fle ang-Shi )0	one-sided) ming Analog h-DeCani (γ Jser-Enterec	= 1.5)
Sim Power	N	μ	μ0	σ	Target Alpha	Sim Alpha
0.784	60	116	125	25	0.025	0.021
0.890	80	116	125	25	0.025	0.019
0.943	100	116	125	25	0.025	0.021
0.970	120	116	125	25	0.025	0.025
0.989	140	116	125	25	0.025	0.036
0.568	60	118	125	25	0.025	0.032
0.694	80	118	125	25	0.025	0.026
0.796	100	118	125	25	0.025	0.017
0.858	120	118	125	25	0.025	0.023
0.894	140	118	125	25	0.025	0.018
0.311	60	120	125	25	0.025	0.019
0.386	80	120	125	25	0.025	0.024
0.500	100	120	125	25	0.025	0.012
0.563	120	120	125	25	0.025	0.037
0.641	140	120	125	25	0.025	0.023

# Plots Section for Power and Sample Size Summary



The power curve plot shows the effect of sample size and means on the power for each scenario.

# Example 4 – Finding Power with Binding Futility Boundaries

[Please note that this example has a calculation time of several minutes to an hour or more.]

Following the setup of Example 3, we wish to see the effect on power of changing from non-binding futility boundaries to binding futility boundaries.

# Setup

If the procedure window is not already open, use the PASS Home window to open it. The parameters for this example are listed below and are stored in the **Example 4** settings file. To load these settings to the procedure window, click **Open Example Settings File** in the Help Center or File menu.

Solve For	Power
Alpha	
N	
μ	
μ0	
σ	
Maximum Number of Stages (K)	5
Info. Proportion at each Stage	Equally incremented
Boundaries Used	One-sided Efficacy with Futility
Hypothesis Direction	Ηa: μ - μ0 < 0
Boundary Specification	Spending Function Calculation
Alpha Spending Function	O'Brien-Fleming Analog
Skipped Efficacy Stages	<empty></empty>
Design Beta	0.10
Beta Spending Function	Ηwang-Shih-DeCani (γ)
γ	1.5
Skipped Futility Stages	< <empty></empty>
Binding or Non-Binding Futility	Binding
Options Tab	
Number of Simulations	
Random Seed	<b>7055400</b> (for Reproducibility)
After Boundary Crossing	Hold out
Boundary Reports Tab	
All Reports	Chasked

t-Statistic vs Information	Checked
t-Statistic vs Stage	Checked
t-Statistic vs N	Checked
Summary Reports Tab	Checked
Summary Plots Tab	

# Output

Click the Calculate button to perform the calculations and generate the following output. The simulation results will differ slightly for each separate run.

### **Scenario Reports**

All the scenario reports for each of the 15 scenarios are generated in the output, but they are not shown here.

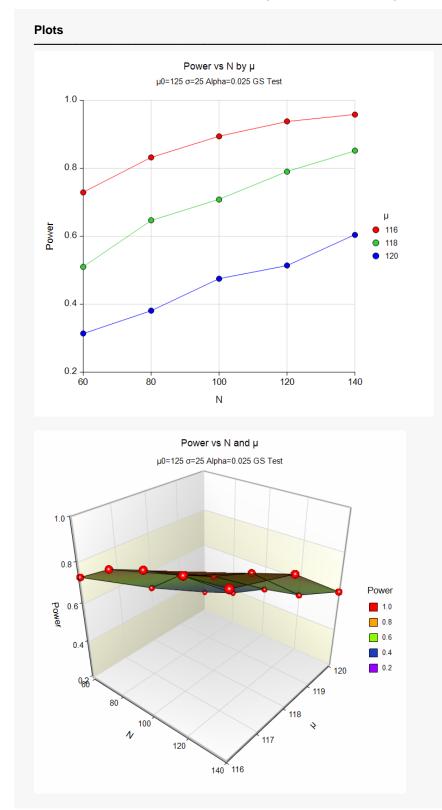
### Power and Sample Size Summary

#### Power and Sample Size Summary

Solve For:	Power
Maximum Number of Stages:	5
Alternative Hypothesis:	$\mu$ - $\mu$ 0 < 0 (one-sided)
Alpha Spending Function:	O'Brien-Fleming Analog
Beta Spending Function:	Hwang-Shih-DeCani (γ = 1.5)
Number of Simulations:	1000
Random Seed:	7055400 (User-Entered)

Sim Power	N	μ	μ0	σ	Target Alpha	Sim Alpha
0.729	60	116	125	25	0.025	0.030
0.832	80	116	125	25	0.025	0.028
0.894	100	116	125	25	0.025	0.029
0.938	120	116	125	25	0.025	0.032
0.958	140	116	125	25	0.025	0.024
0.510	60	118	125	25	0.025	0.027
0.647	80	118	125	25	0.025	0.024
0.708	100	118	125	25	0.025	0.030
0.790	120	118	125	25	0.025	0.022
0.852	140	118	125	25	0.025	0.027
0.314	60	120	125	25	0.025	0.030
0.381	80	120	125	25	0.025	0.026
0.475	100	120	125	25	0.025	0.031
0.514	120	120	125	25	0.025	0.026
0.604	140	120	125	25	0.025	0.032

# Plots Section for Power and Sample Size Summary



If the power results are compared to those with non-binding futility boundaries in Example 3, it is seen that the power for binding futility boundaries is several percent lower. Higher numbers of simulations might be used to fine-tune these differences.

# **Example 5 – Comparing Numbers of Stages**

[Please note that each run will take a few to several minutes.]

Following the setup of Example 3, we wish to see the effect on power of changing the number of stages. This requires multiple runs with different numbers of stages. The numbers of stages examined here are 2, 3, 4, 5, 10 and 20. A mean of 118 and a sample size of 100 will be considered.

## Setup

If the procedure window is not already open, use the PASS Home window to open it. The parameters for this example are listed below and are stored in the **Example 5** settings file. To load these settings to the procedure window, click **Open Example Settings File** in the Help Center or File menu.

Design Tab	
Solve For	Power
Alpha	0.025
N	100
μ	118
μ0	125
σ	25
Maximum Number of Stages (K)	<b>2</b> (Also run with <b>3</b> , <b>4</b> , <b>5</b> , <b>10</b> , and <b>20</b> )
Info. Proportion at each Stage	Equally incremented
Boundaries Used	One-sided Efficacy with Futility
Hypothesis Direction	Ha: μ - μ0 < 0
Boundary Specification	Spending Function Calculation
Alpha Spending Function	O'Brien-Fleming Analog
Skipped Efficacy Stages	<empty></empty>
Design Beta	0.10
Beta Spending Function	Hwang-Shih-DeCani (γ)
γ	1.5
Skipped Futility Stages	
Binding or Non-Binding Futility	Non-Binding
Options Tab	
Number of Simulations	10000
Random Seed	Random
After Boundary Crossing	Hold out
Boundary Reports Tab	
All Reports	Checked
Boundary Plots Tab	
t-Statistic vs Information	Checked
t-Statistic vs Stage	Checked
t-Statistic vs N	

Summary Reports Tab	
All Reports	Checked
Summary Plots Tab	
All plots	<b>Checked</b> (only 2D will be used)

# Output

Click the Calculate button to perform the calculations and generate the following output. Each run will likely take a few minutes. The simulation results will differ slightly for each separate run.

### **Scenario Reports**

All the scenario reports for each of the 6 scenarios are generated in the output, but they are not shown here.

### Power and Sample Size Summary

Alternativ Alpha Sp Beta Spe	n Numbe ve Hypotl ending Fuending Fuending Fue	unction:	μ -   Ο'Β Ηwa	4 5 10 2 u0 < 0 ( rien-Fle ang-Shil	20 (separate one-sided) ming Analog h-DeCani (γ	)	
	Number of Simulations: 10000						
Sim Power	N	μ	μ0	σ	Target Alpha	Sim Alpha	Number of Stages
0.7047	100	118	125	25	0.025	0.0252	2
0.7917		440	125	25	0.025	0.0249	3
0.7917	100	118	120				
	100 100	118 118	125	25	0.025	0.0252	4
0.7889				25 25	0.025 0.025	0.0252 0.0249	4 5
0.7889 0.7853	100	118	125	-			

It is seen that the impact of the number of stages on the overall power is very minor.

# Example 6 – Two-Sided Boundaries

[Please note that this example has a calculation time of several minutes.]

Suppose that the scenario is similar to the setup of Example 3, but the boundary structure is changed to twosided boundaries with an alpha of 0.05.

# Setup

If the procedure window is not already open, use the PASS Home window to open it. The parameters for this example are listed below and are stored in the **Example 6** settings file. To load these settings to the procedure window, click **Open Example Settings File** in the Help Center or File menu.

Solve For	Power
Alpha	0.05
N	
μ	
μ0	
σ	
Maximum Number of Stages (K)	5
Info. Proportion at each Stage	Equally incremented
Boundaries Used	Two-sided Efficacy with Futility (Symmetric)
Boundary Specification	Spending Function Calculation
Alpha Spending Function	O'Brien-Fleming Analog
Skipped Efficacy Stages	< <empty></empty>
Design Beta	0.10
Beta Spending Function	Hwang-Shih-DeCani (γ)
γ	1.5
Skipped Futility Stages	<empty></empty>
Binding or Non-Binding Futility	Non-Binding
Overlapped Futility Boundaries	Remove (skip) overlapped futility boundaries
Options Tab	
Number of Simulations	
Random Seed	,
After Boundary Crossing	Hold out
Boundary Reports Tab	
All Reports	Checked
Boundary Plots Tab	
t-Statistic vs Information	Checked
t-Statistic vs Stage	Checked
t-Statistic vs N	Checked

Summary Reports Tab		
All Reports	Checked	
Summary Plots Tab		
All plots	Checked	

# Output

Click the Calculate button to perform the calculations and generate the following output. The simulation results will differ slightly for each separate run.

### Run Summary Report – Scenario 1

#### **Run Summary Report - Scenario 1**

Item	Value
Solve For	Power
Maximum Number of Stages (Design)	5
Current Stage	0
Alternative Hypothesis	$\mu - \mu 0 \neq 0$ (two-sided, symmetric)
Alpha Spending Function	O'Brien-Fleming Analog
Beta Spending Function	Hwang-Shih-DeCani (γ = 1.5)
Futility Boundaries	Non-Binding
Target Alpha	0.05
Alpha (from simulations)	0.043
μ	116
μΟ	125
σ	25
N (if final stage reached)	60
Power (from simulations)	0.677
Maximum Information	0.096

## t-Value Boundaries – Scenario 1

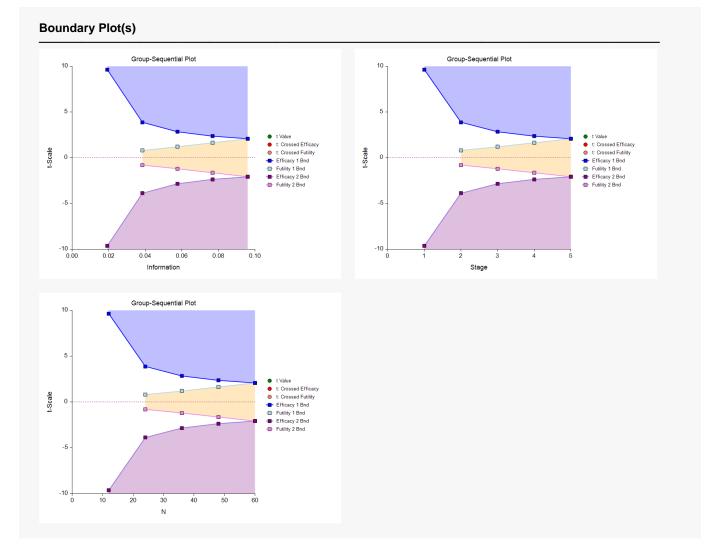
### t-Value Boundaries

Maximum Information:	0.096
Alternative Hypothesis:	$\mu$ - $\mu$ 0 $\neq$ 0 (two-sided, symmetric)
Futility Boundaries:	Non-Binding

Stage	Upper	Side	Lower	Information	
	Efficacy 1	Futility 1	Efficacy 2	Futility 2	Information Proportion
1	9.6285		-9.6285		0.2
2	3.8640	0.8049	-3.8640	-0.8049	0.4
3	2.8459	1.2104	-2.8459	-1.2104	0.6
4	2.3683	1.6418	-2.3683	-1.6418	0.8
5	2.0761	2.0761	-2.0761	-2.0761	1.0

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# Boundary Plot(s) – Scenario 1



### **Other Scenario Reports**

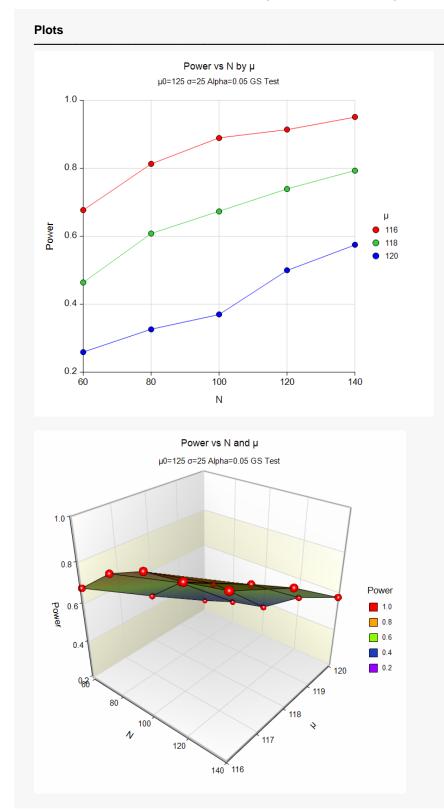
All of the scenario reports for each of the 15 scenarios are generated in the output, but they are not shown here.

# Power and Sample Size Summary

### Power and Sample Size Summary

Solve Fo	Solve For:			Power				
Maximum Number of Stages:		es: 5						
Alternativ	Alternative Hypothesis:		μ-	µ0 ≠ 0 (†	two-sided, s	ymmetric)		
Alpha Sp	pending F	unction:	O'B	rien-Fle	ming Analog	9		
Beta Spe	Beta Spending Function:		Hwa	Hwang-Shih-DeCani (γ = 1.5)				
Number	of Simula	tions:	100	0				
Random	Seed:		605	4000 (L	Jser-Enterec	1)		
Sim					Target	Sim		
Power	Ν	μ	μ0	σ	Alpha	Alpha		
0.677	60	116	125	25	0.05	0.043		
0.813	80	116	125	25	0.05	0.047		
0.889	100	116	125	25	0.05	0.030		
0.914	120	116	125	25	0.05	0.059		
0.951	140	116	125	25	0.05	0.032		
0.464	60	118	125	25	0.05	0.040		
0.608	80	118	125	25	0.05	0.040		
0.673	100	118	125	25	0.05	0.029		
0.739	120	118	125	25	0.05	0.028		
0.793	140	118	125	25	0.05	0.032		
0.259	60	120	125	25	0.05	0.030		
0.326	80	120	125	25	0.05	0.036		
0.370	100	120	125	25	0.05	0.036		
0.500	120	120	125	25	0.05	0.032		
0.575	140	120	125	25	0.05	0.031		

# Plots Section for Power and Sample Size Summary



The power curve plot shows the effect of sample size and mean difference on the power for each scenario.

# Example 7 – Validation Using O'Brien-Fleming Analog Boundaries

Reboussin (1992) presents a two-sample example for normally distributed data for a design with two-sided O'Brien-Fleming boundaries, 5 stages, alpha = 0.05, beta = 0.10,  $\mu$ 1 = 220,  $\mu$ 2 = 200,  $\sigma$ 1 and  $\sigma$ 2 = 30. The upper boundaries are: 4.8769, 3.3569, 2.6803, 2.2898, 2.0310. To show that PASS provides the same boundary values for the underlying z-value boundaries, enter the following.

# Setup

If the procedure window is not already open, use the PASS Home window to open it. The parameters for this example are listed below and are stored in the **Example 7** settings file. To load these settings to the procedure window, click **Open Example Settings File** in the Help Center or File menu.

Design Tab	
Solve For	Sample Size
Power	0.90
Alpha	0.05
μ	
μ0	
σ	
Maximum Number of Stages (K)	5
Info. Proportion at each Stage	Equally incremented
Boundaries Used	Two-sided Efficacy Only (Symmetric)
Boundary Specification	Spending Function Calculation
Alpha Spending Function	O'Brien-Fleming Analog
Skipped Efficacy Stages	<empty></empty>
Options Tab	
Number of Simulations	
Random Seed	
After Boundary Crossing	Hold out
Boundary Reports Tab	
All Reports	Checked
Boundary Plots Tab	
t-Statistic vs Information	Checked
t-Statistic vs Stage	Checked
t-Statistic vs N	Checked
Summary Reports Tab	
All Reports	Checked

# Output

Click the Calculate button to perform the calculations and generate the following output. The simulation results will differ slightly for each separate run.

### **Run Summary Report**

#### **Run Summary Report**

Item	Value
Solve For	Sample Size
Maximum Number of Stages (Design)	5
Current Stage	0
Alternative Hypothesis	$\mu - \mu 0 \neq 0$ (two-sided, symmetric)
Alpha Spending Function	O'Brien-Fleming Analog
Target Alpha	0.05
Alpha (from simulations)	0.053
μ	220
μΟ	200
σ	30
N (if final stage reached)	28
Target Power	0.9
Power (from simulations)	0.928
Maximum Information	0.0311

## **Underlying Z Scale Boundaries**

#### **Underlying Z Scale Boundaries**

Maximum Information:	0.0311
Alternative Hypothesis:	μ - μ0 ≠ 0 (two-sided, symmetric)
Bound	daries

Stage			Information
	Efficacy 1	Efficacy 2	Proportion
1	4.8769	-4.8769	0.2
2	3.3569	-3.3569	0.4
3	2.6803	-2.6803	0.6
4	2.2898	-2.2898	0.8
5	2.0310	-2.0310	1.0

The boundary values match those of Reboussin (1992) exactly.